Lecture	Торіс
L1	INTRODUCTION TO SUBJECT
L2	EVOLUTION OF MOBILE RADIO COMMUNICATIONS
L3	EXAMPLES OF WIRELESS COMM. SYSTEMS, PAGING SYSTEMS
L4	CORDLESS
	TELEPHONESYSTEMS, COMPARISONOFVARIOUSWIRELESSSYSTEMS.
L5	SECOND GENERATION CELLULAR NETWORKS, THIRD GENERATION
	WIRELESS NETWORKS
L6	WIRELESS IN LOCAL LOOP, WIRELESS LOCAL AREA NETWORKS
L7	BLUETOOTH AND PERSONALAREANETWORKS.
L8	REVISION OF UNIT 1
L9	SPECTRUM ALLOCATION, BASIC CELLULAR SYSTEMS
L10	PERFORMANCE CRITERIA, OPERATION OF CELLULAR SYSTEMS
L11	ANALOGCELLULARSYSTEMS, DIGITALCELLULARSYSTEMS.
L12	FREQUENCY REUSE, CHANNEL ASSIGNMENT STRATEGIES,
L13	HANDOFF STRATEGIES, INTERFERENCE AND SYSTEM CAPACITY,
L14	TRACKING AND GRADE OFF SERVICE
L15	IMPROVINGCOVERAGE AND CAPACITY.
L16	REVISION OF UNIT 2
L17	DISCUSSION OF SESSIONAL 1
L18	INTRODUCTION TO MULTIPLE ACCESS
L19	FDMA
L20	TDMA
L21	SPREAD SPECTRUM MULTIPLE ACCESS
L22	SPACE DIVISION MULTIPLE ACCESS
L23	PACKETRATIO, CAPACITY OFA CELLULARSYSTEMS.
L24	REVISION OF UNIT 3
L25	GSM
L26	IS-95
L27	UMTS-IMT-2000
L28	SIGNALING, CALL CONTROL
L29	MOBILITYMANAGEMENT AND LOCATIONTRACING.
L30	REVISION OF UNIT 4
L31	DISCUSSION OF SESSIONAL 2
L32	CONTENT BEYOND CURRICULUM

- Lecture Topic
- L1 Microwave Resonators: Brief description of waveguides
- L2 Coplanar waveguides
- L3 Cavity resonators: rectangular, cylindrical,
- L4 Cavity resonators: spherical and coaxial
- L5 Excitation and coupling of cavities
- L6 Q-factor.
- L7 Microwave Measurements: Measurement of Frequency
- L8 Measurement of Impedance (using slotted section), attenuation,
- L9 Microwave Measurements: power, dielectric constant
- L10 Measurement of V.S.W.R.
- L11 Measurement of Insertion loss and permeability
- L12 Microwave Generators: Construction, characteristics
- L13 operating principle and typical applications of Klystron (two cavity, multicavity)
- L14 Reflex Klystron
- L15 Magnetron (Cylindrical magnetron and description of Π mode applications)
- L16 Magnetron (Cylindrical magnetron and description of  $\Pi$  mode applications) contd.
- L17 Traveling Wave Tube(TWT).
- L18 Matrix Description of Microwave Circuits: Scattering Matrix: properties
- L19 Measurement of scattering coefficients
- L20 Scattering matrices for common microwave systems
- L21 Microwave Components: Waveguide tees- E-plane
- L22 H-plane, magic tee
- L23 rat race, directional coupler
- L24 Tuning screws and stubs
- L25 Isolators and circulators- their constructional features
- L26 Isolators and circulators- Applications
- L27 Microwave filters, Phase shifters
- L28 Attenuators and frequency meter.
- L29 Solid State Microwave Devices: Transferred Electron Devices-Gunn Effect
- L30 Negative differential resistance phenomenon
- L31 Field domain formation
- L32 Gunn diode structure
- L33 Avalanche transit time devices
- L34 IMPATT diode
- L35 TRAPATT, BARITT diodes
- L36 Parametric amplifiers.

LECTURE	TOPIC
L1	Definition of Transducer
L2	Advantages of an Electrical Signal as Output
L3	Basic Requirements of Transducers
L4	Primary and Secondary Transducer.
L5	Analog or Digital Types of Transducers
L6	Resistive
L7	Inductive
L8	Capacitive
L9	Piezoelectric
L10	Photoelectric
L11	Hall Effect Transducers
L12	Measurement of Pressure- Manometers
L13	Force Summing Devices and Electrical Transducers
L14	Measurement of Temperature- Metallic Resistance Thermometers
LI 5	Semi Conductor Resistance Sensors
L16	Thermistors
L1T	Thermoelectric Sensors
L18	Pyrometers
L19	Measurement of Displacement- Potentiometric Resistance Type Transducers
L20	Inductive Type Transducers
L21	Differential Transformer (LVDT)
L22	Capacitive Transducers
L23	Hall Effect Devices
L24	Strain Gauge Transducers
L25	Measurement of Velocity- Variable Reluctance Pick Up
L26	Electromagnetic Tachometers
L27	Photoelectric Tachometer
L28	Toothed Rotor Tachometer Generator
L29	Measurement of Force - Strain Gauge Load Cells
L30	Pneumatic Load Cell
L31	LVDT Type Force Transducer
L32	Measurement of Torque-Torque Meter
L33	Torsion Meter
L34	Absorption Dynamometers
L35	Inductive Torque Transducer
L36	Digital Methods

	LECIUKE PLAN
LECTURE	TOPIC
L1	Radar Basics: Radar Block Diagram & operation
L2	Application of Radar
L3	Simple form of Radar Equation,
L4	Minimum Detectable Signal
L5	Receiver Noise
L6	Signal to Noise Ratio
L7	Transmitter Power
L8	Pulse Repetition Frequency
L9	Range Ambiguities
L10	System Losses
L11	Propagation effects
L12	CW & Frequency Modulated Radar, The Doppler Effect
L13	CW Radar
L14	FM- CW Radar
L15	Multiple Frequency CW Radar
L16	Introduction to MTI and Pulse Doppler Radar
L17	Delay Line Cancellors, Multiple or Staggered
LI 8	Pulse Repetition frequencies
LI 9	Range-Gated Doppler Filters
L20	MTI Delay Line
L21	Limitation of MTI performance
L22	Noncoherent MTI Pulse, Doppler Radar
L23	MTI from a moving platform
L24	Tracking with Radar
L25	Sequential Lobbing
L26	Conical Scan
L27	Monopulse Tracking Radar
L28	Tracking in range
L29	Acquisition
L30	Introduction to Receivers, Displays & Duplexers
L31	Radar Receivers
L32	Noise Figure
L33	Mixer
L34	Low-Noise Front Ends
L35	Displays
L36	Duplexer, Receiver Protectors